



Quorum

Gary Koob



Quorum Goal



Deliver Assured Dynamic Response to Mission-Critical Applications in the Presence of Mixed Workloads

Command & Control

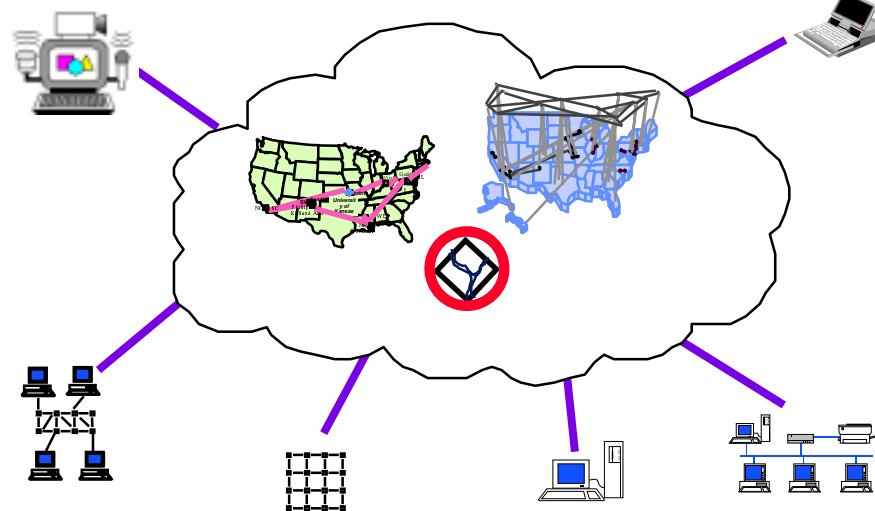


Soft Real-Time

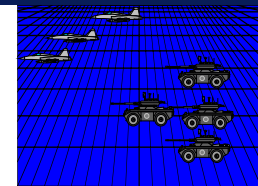
Combat Control



Hard Real-Time

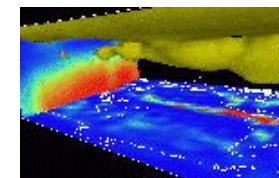


Modeling & Simulation



Mixed workload

Metacomputing



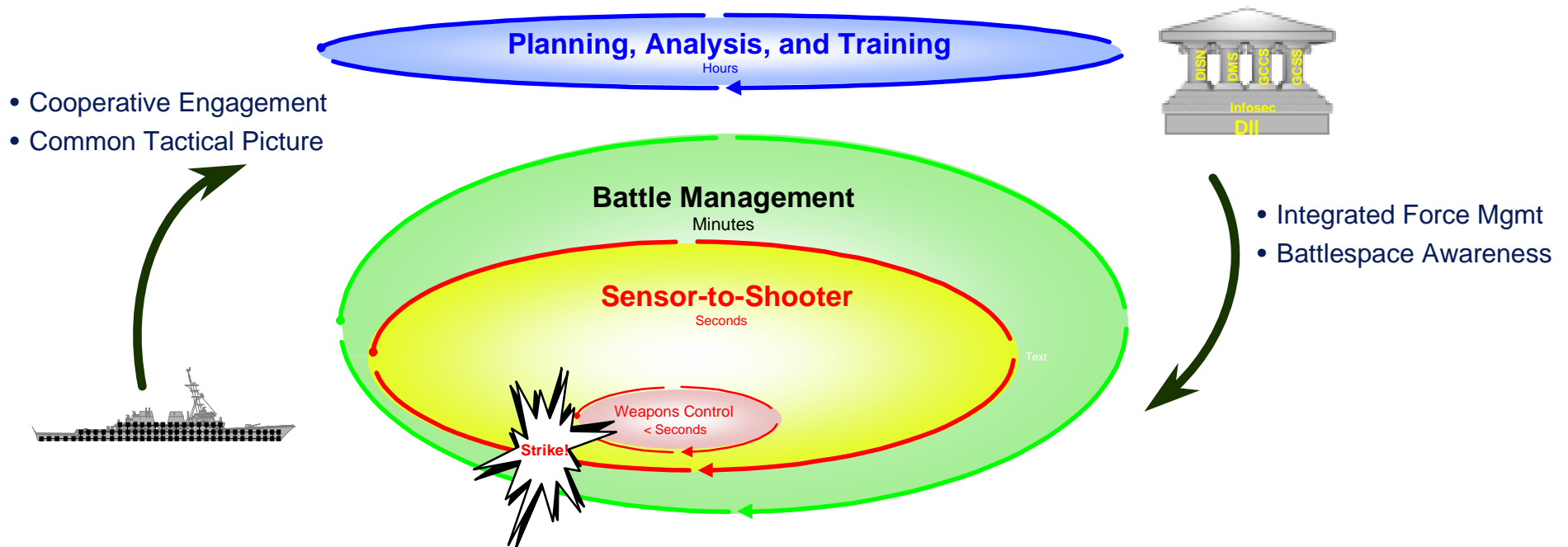
High Performance



Why Mixed Workloads?

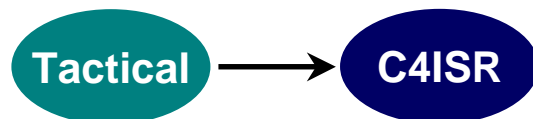
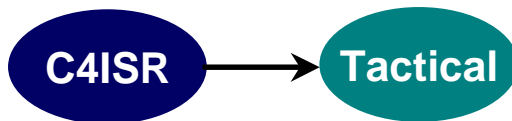


Convergence of Warfighting Domains Requires Coordination Across Multiple Time Scales





Why Mixed Workload?



■ Affordability:

- Applications with different characteristics must share common computing base

■ Rapid Response:

- Shrinking decision cycles demand tight coupling of C4ISR and Tactical Combat Control systems

■ Battlespace Awareness:

- Making real-time track data accessible to C4ISR requires tactical system support for network protocols, object brokers, applications, etc. for interoperability

Impact: “Special purpose OS” must now support general purpose software

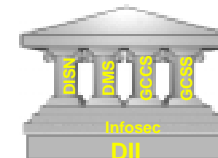


Quorum Bridges the Tactical-C4ISR Gap

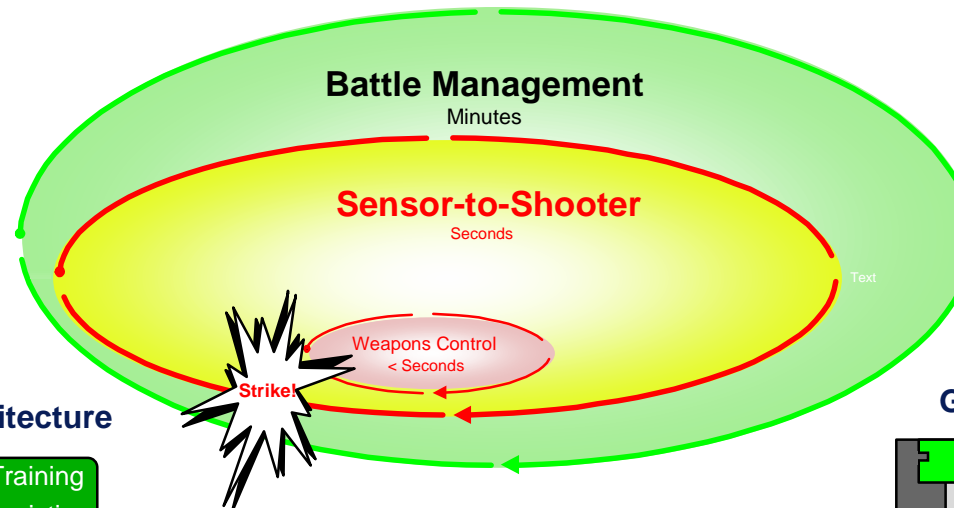


- Cooperative Engagement
- Common Tactical Picture

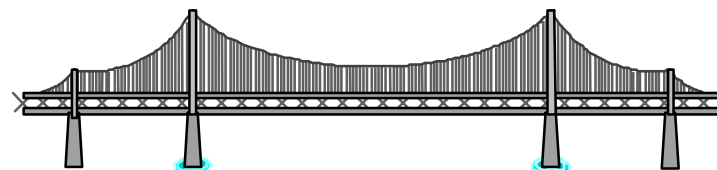
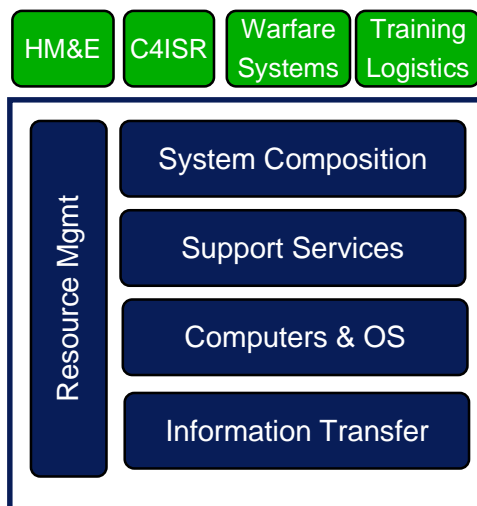
Planning, Analysis, and Training
Hours



- Integrated Force Mgmt
- Battlespace Awareness

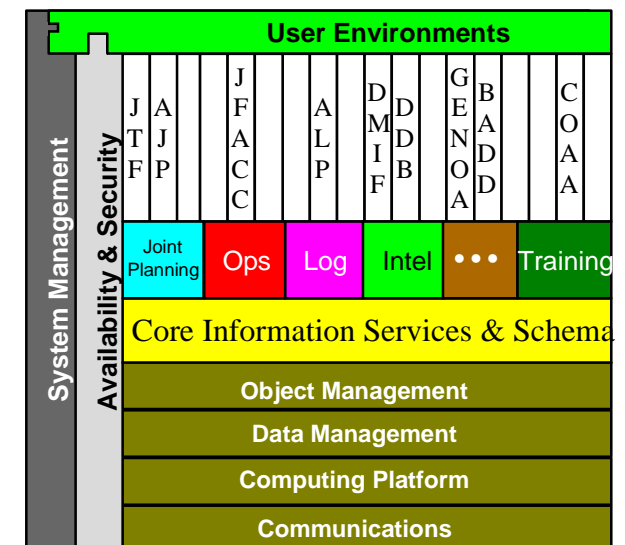


AdCon-21 Notional Architecture



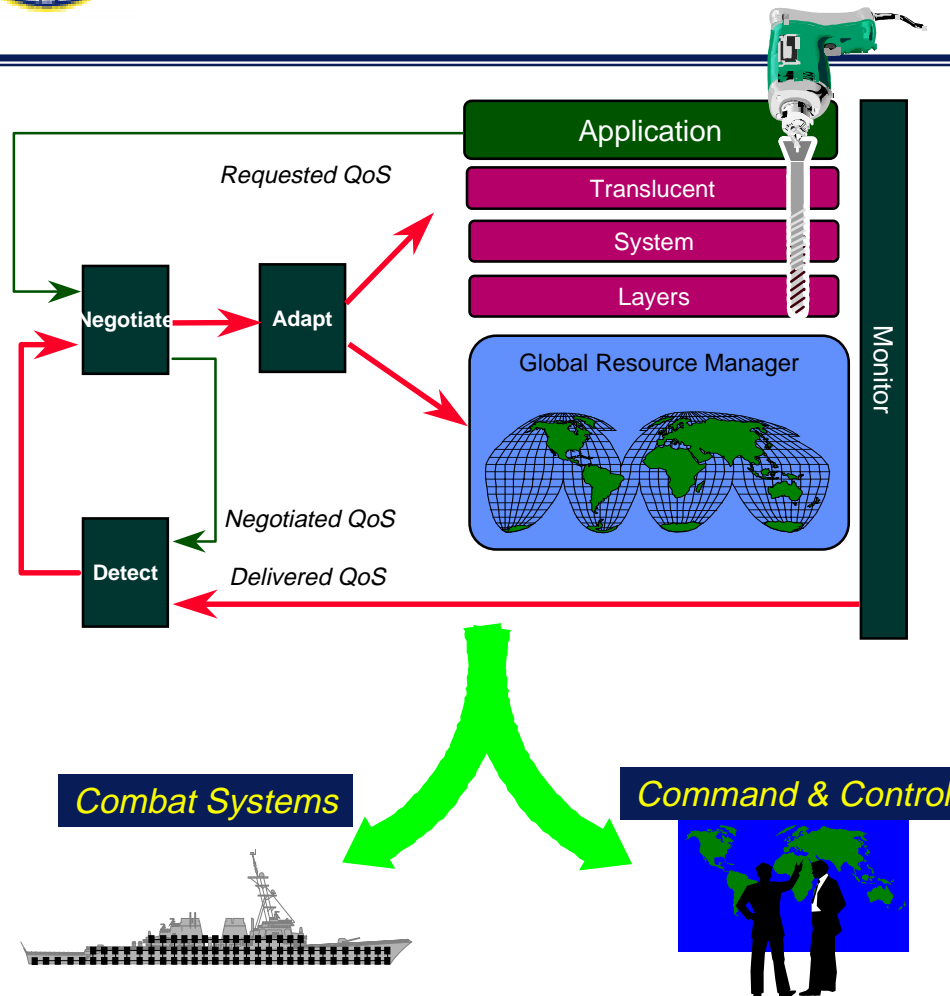
Quorum QoS-Based Technologies
can bridge this gap

GCCS-LES Mid-Term Architecture





Quorum Program



- **Feedback-Based Arch**

- **Translucent Middleware**

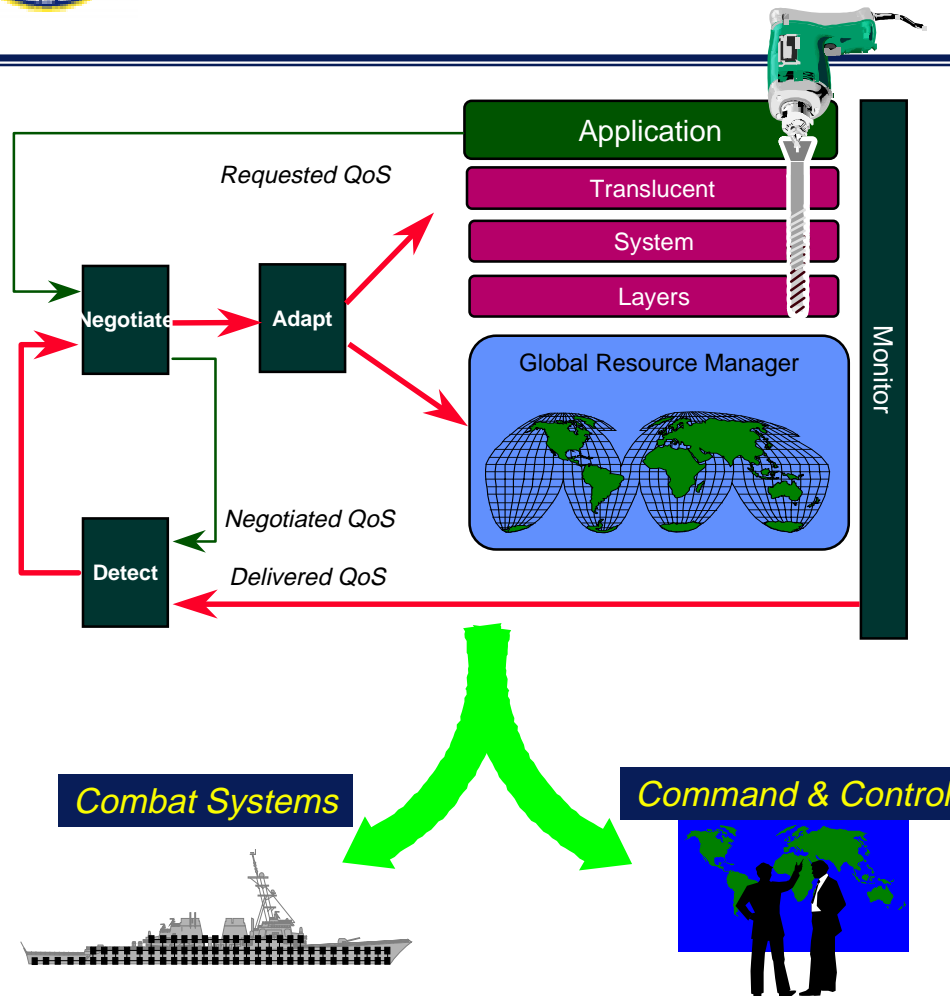
- **Global Resource Manager**

- **Integration**

Quorum Goal: Deliver Assured Dynamic Response to Mission-Critical Applications in the Presence of Mixed Workloads



Quorum Program



■ Feedback-Based Arch

- Negotiated “contracts”
- Dynamic adaptation
- Feedback control

■ Translucent Middleware

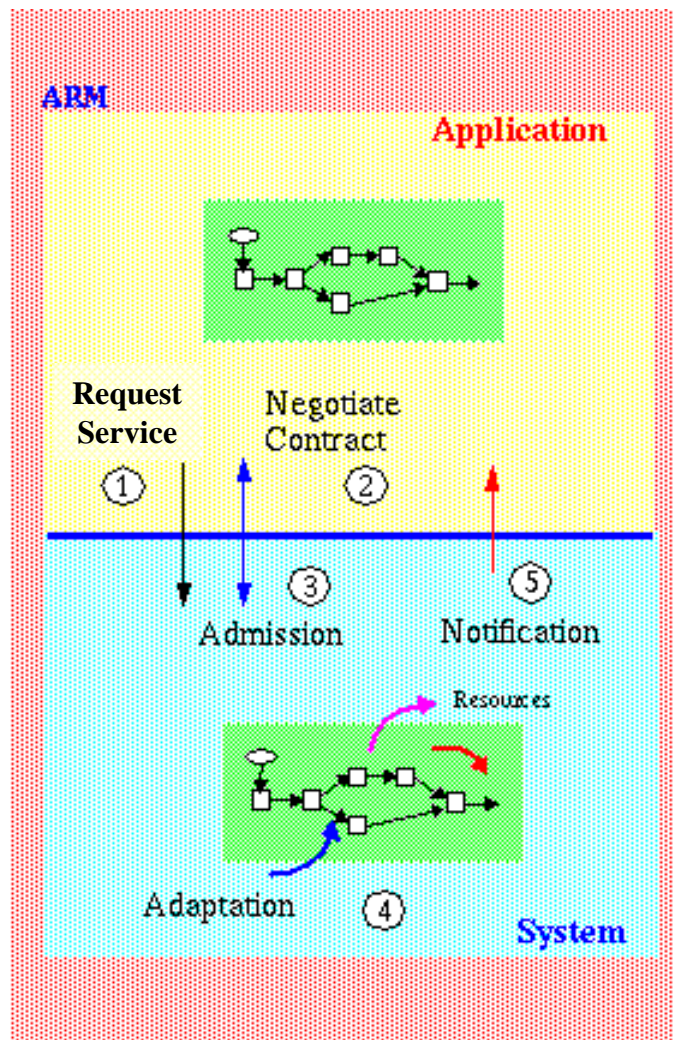
■ Global Resource Manager

■ Integration

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Negotiated Contracts



① Application Requests Service

② Negotiation

- Applications negotiate service specifying acceptable operating region

③ Admission Control

- Application is admitted only if sufficient resources are available within region
- Prevents overloading
- Guarantees real-time tasks

④ Adaptation

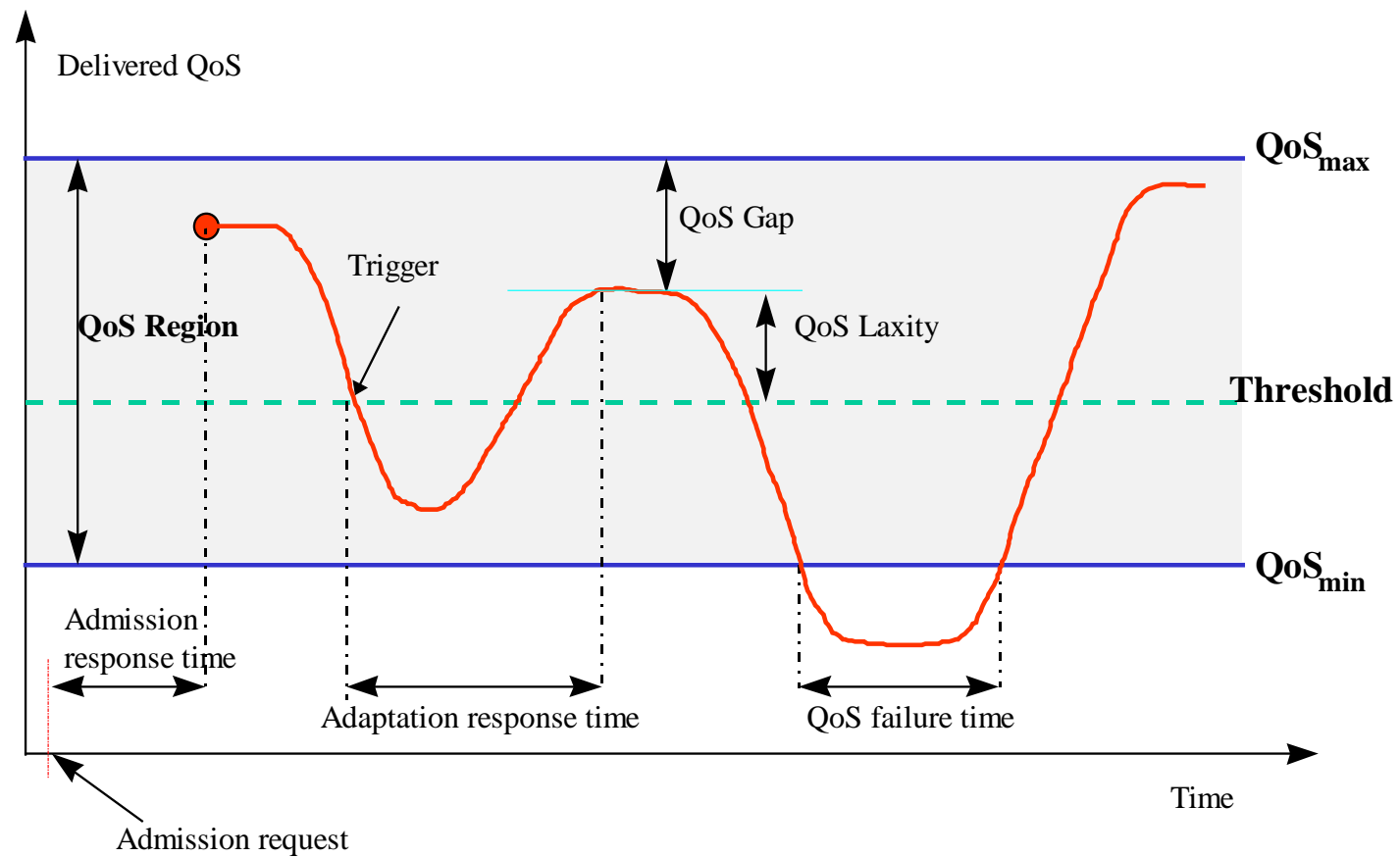
- System adapts to maintain desired region under workload, resource fluctuations

⑤ Notification

- If desired region cannot be maintained, application is notified, may renegotiate

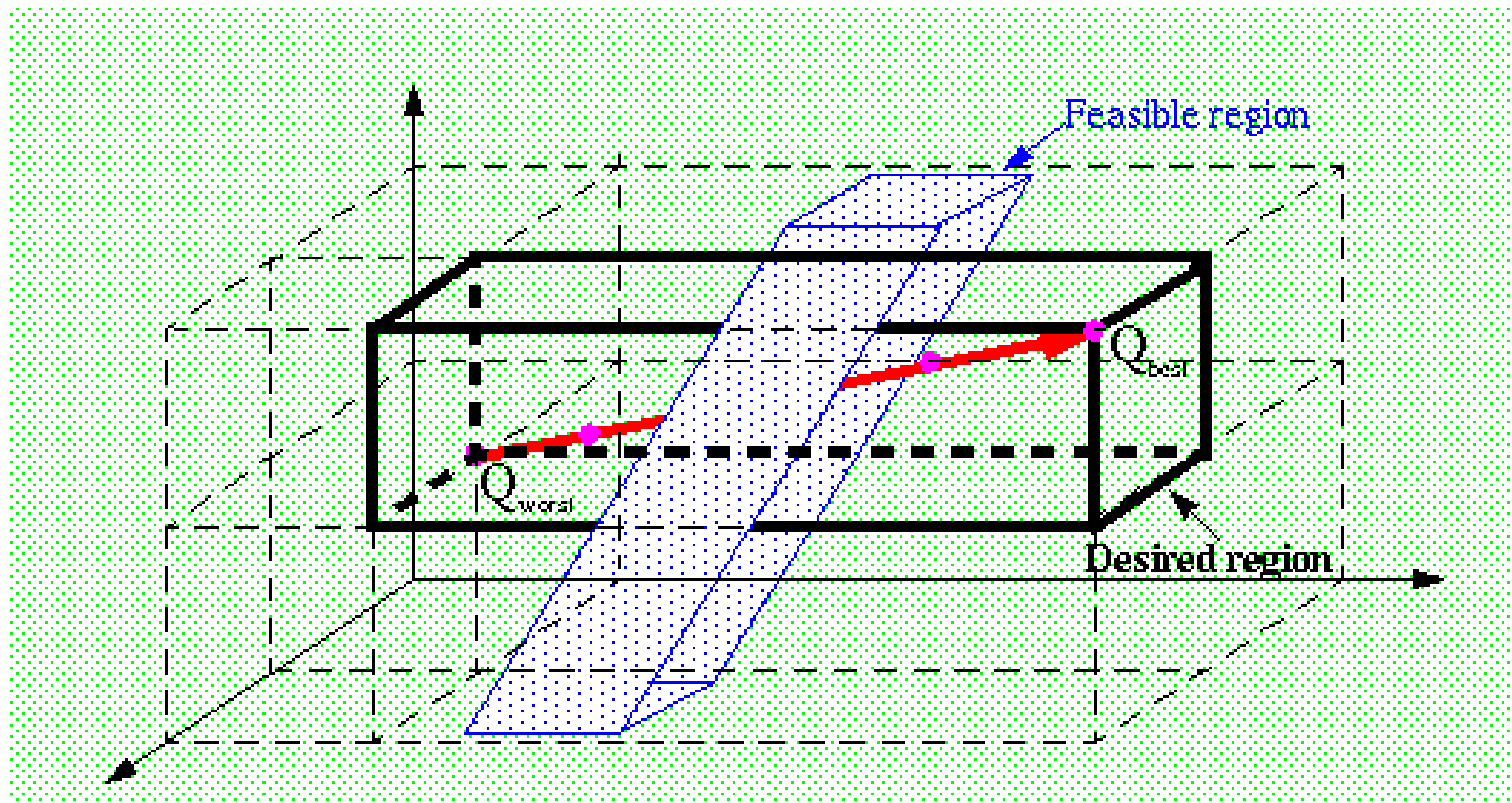


Quality-of-Service Regions





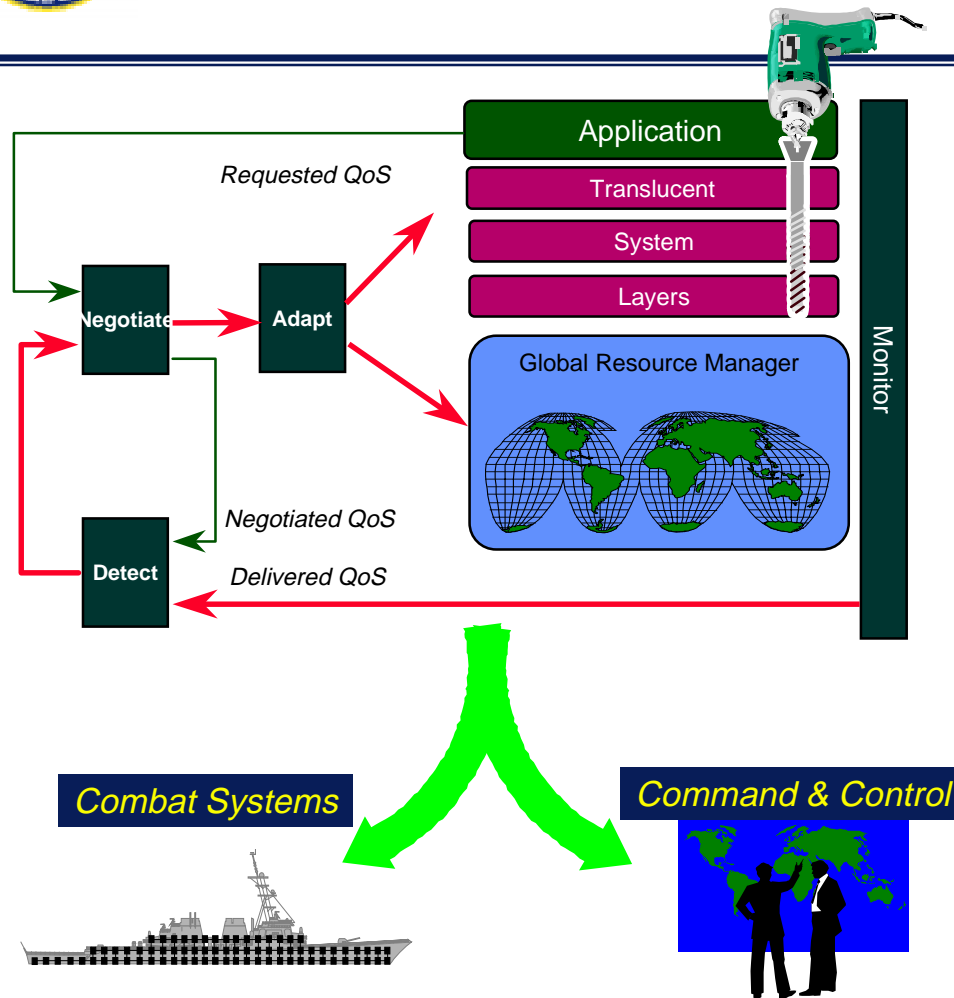
Dynamic Adaptation



- **If desired region cannot be maintained:**
 - Contract may authorize automatic transition to another feasible region (with notification), or
 - Renegotiate with application



Quorum Program



■ Feedback-Based Arch

■ Translucent Middleware

- Constraint propagation
- Cross-layer specialization
- Drill-down technologies

■ Global Resource Manager

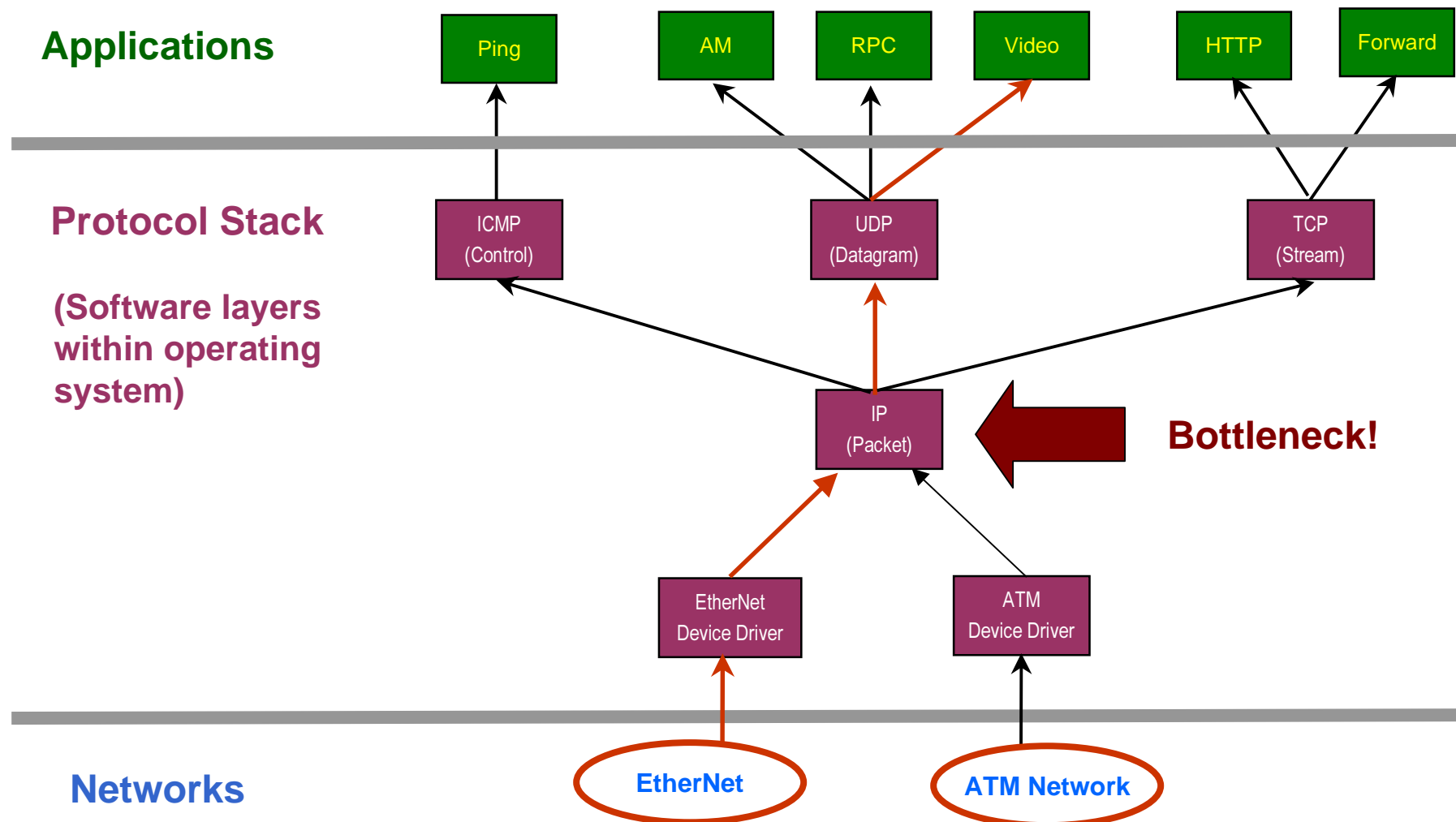
■ Integration

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Constraint Propagation: Why?

Example: Network Protocol Stack

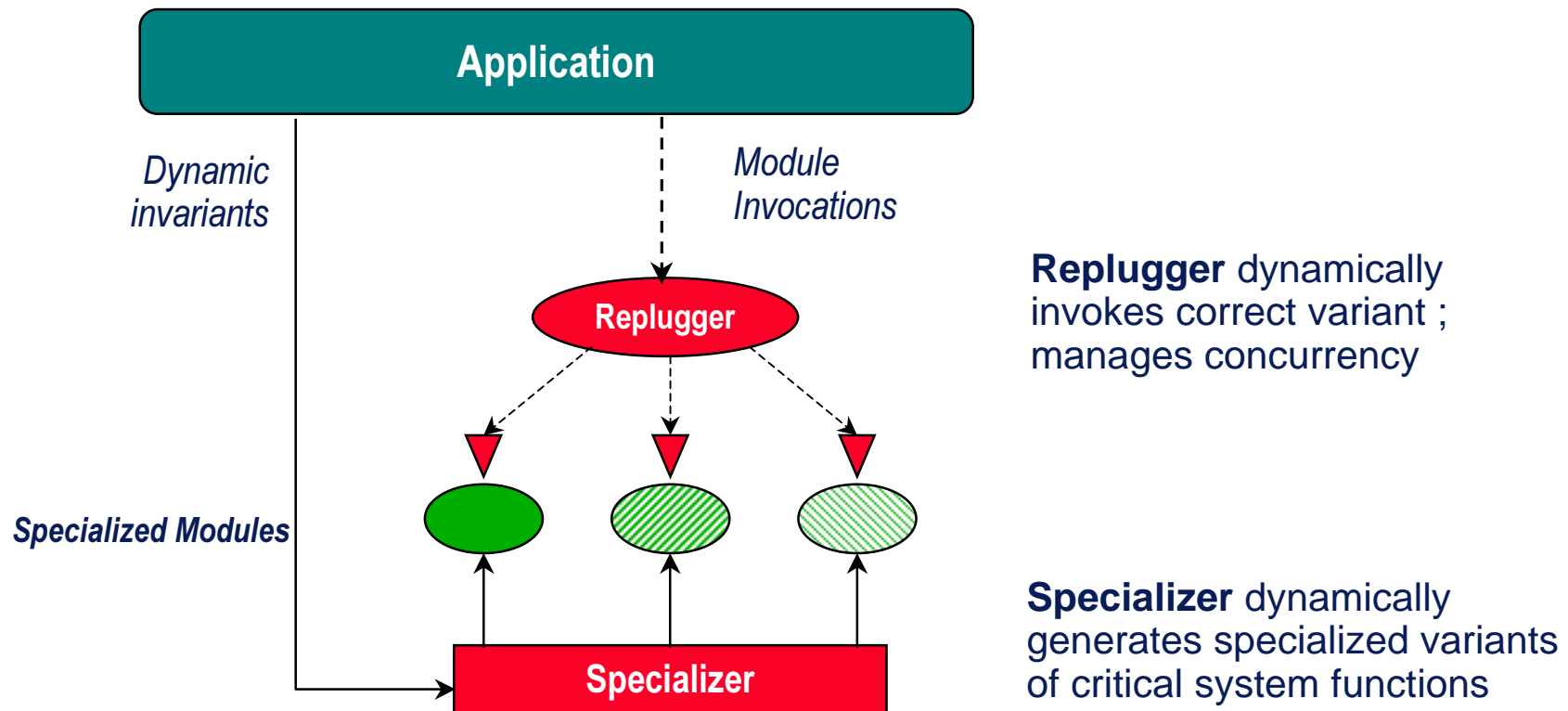




Constraint Propagation: Sample Approach Specialization

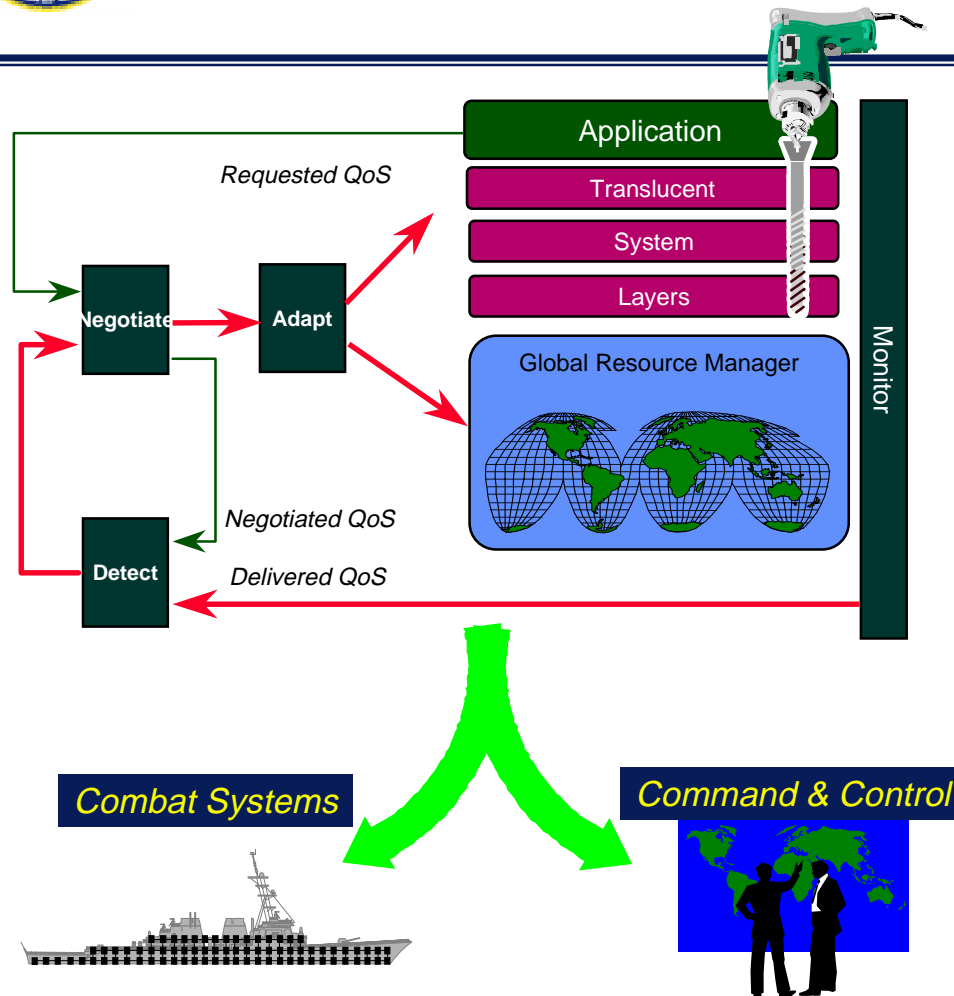


Specialization Tools Dynamically Optimize Paths Through System Code
to Satisfy QoS Constraints





Quorum Program



■ Feedback-Based Arch

■ Translucent Middleware

■ Global Resource Manager

- Dynamic discovery
- Path-based allocation

■ Integration

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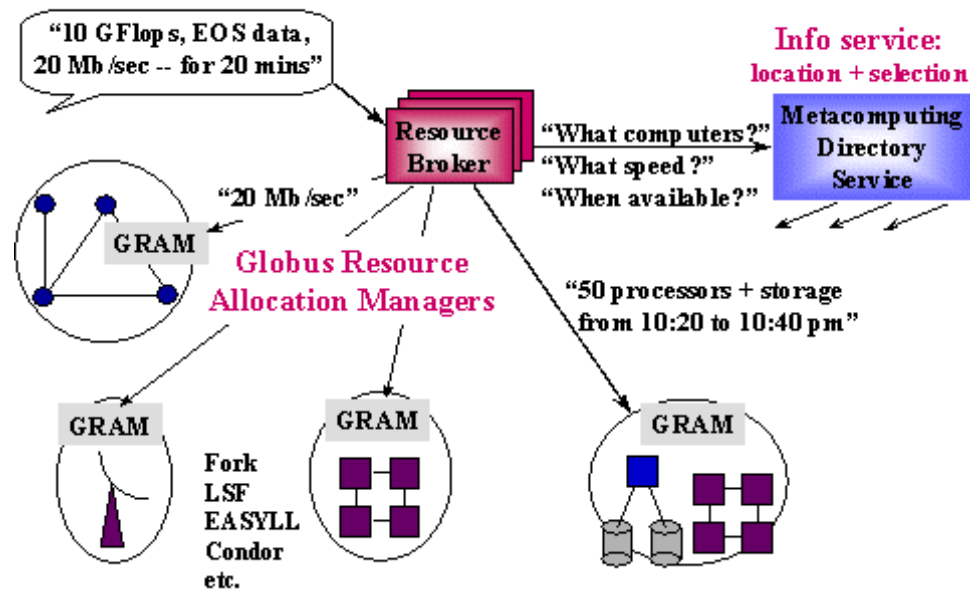


Global Resource Management

Example: Synthetic Forces Simulation



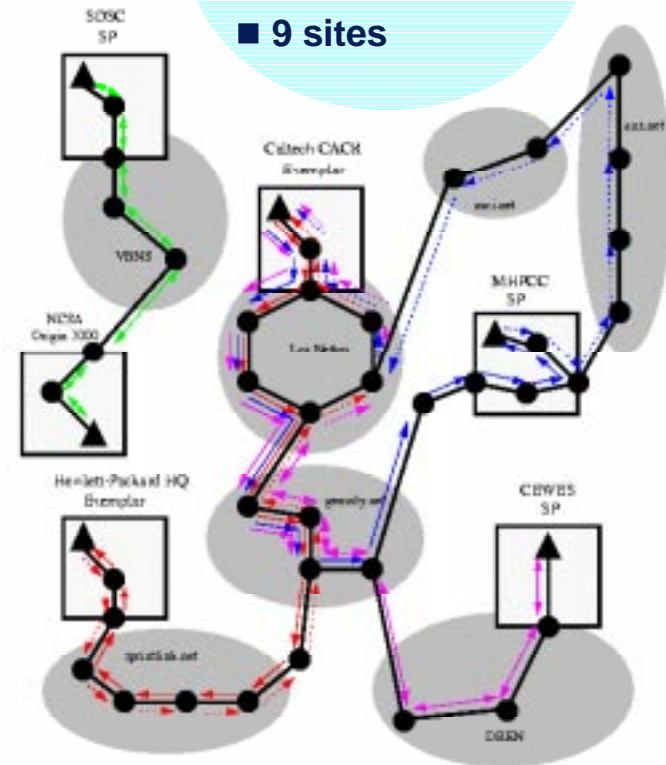
The Globus Project (USC ISI)



- Directory Service collects, disseminates up-to-date resource status info
- Resource Broker translates requests
- Coordinates allocation across sites

SF-Express Demo Record Set at TARA 98

- 100,000 Entities
- 1386 processors
- 9 sites



Quorum Goes to Sea

Transition Target: DD-21 Land Attack Destroyer

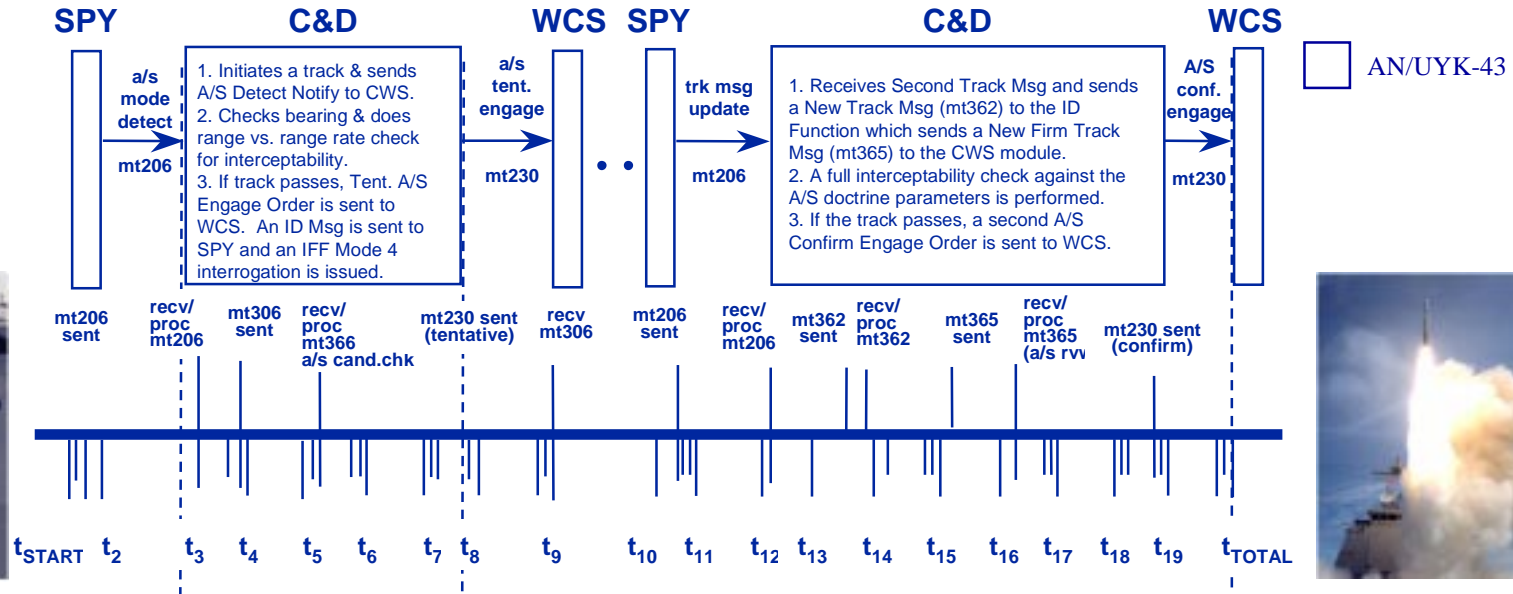




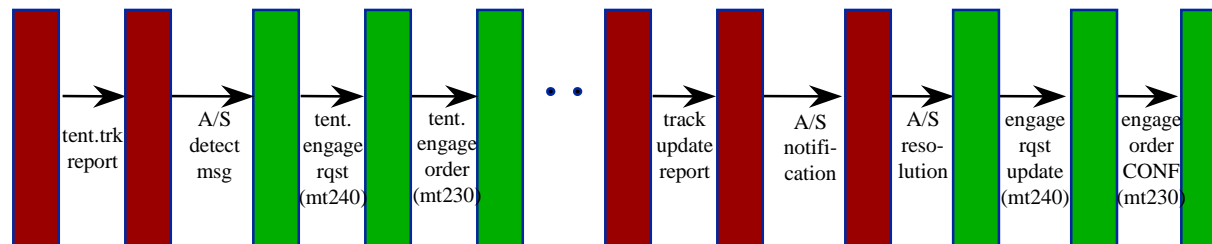
Why DD-21 Needs Assured Response: SPY Radar Auto-Special Time-Line



**CURRENT
AWS**

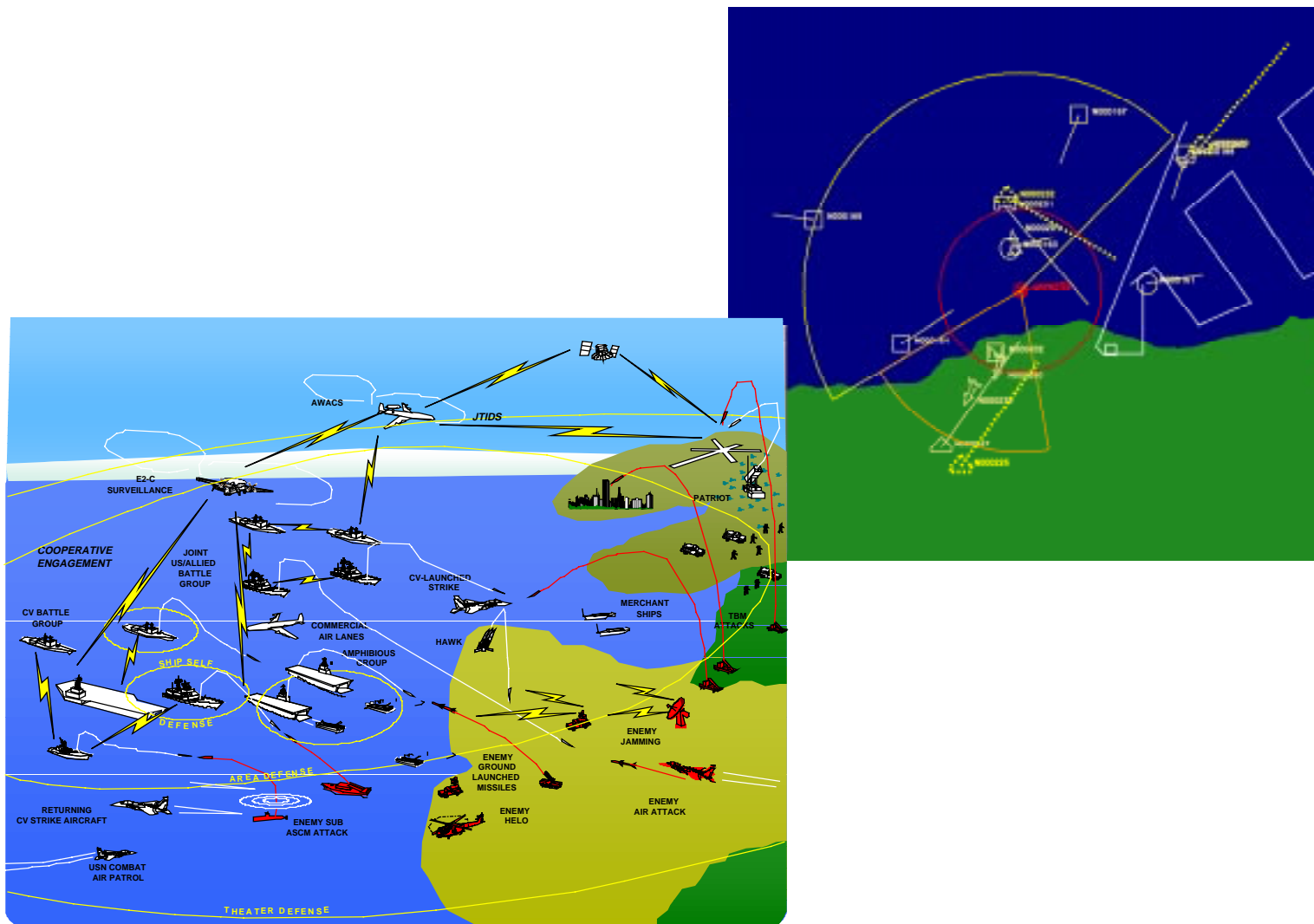


AdCon-21



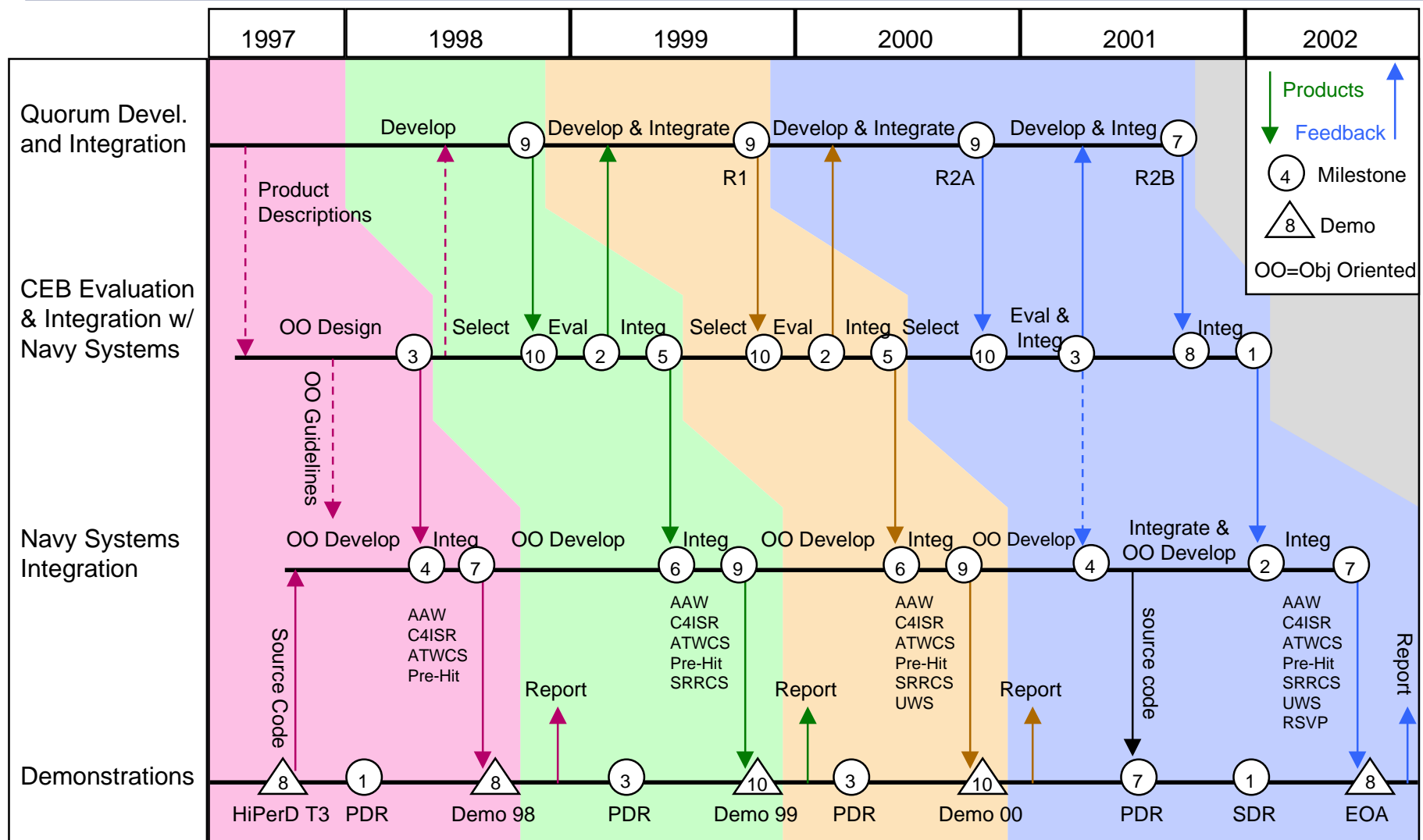


Why DD-21 Needs Mixed Workloads: Integration of Combat & C4ISR in Littoral Battlespace



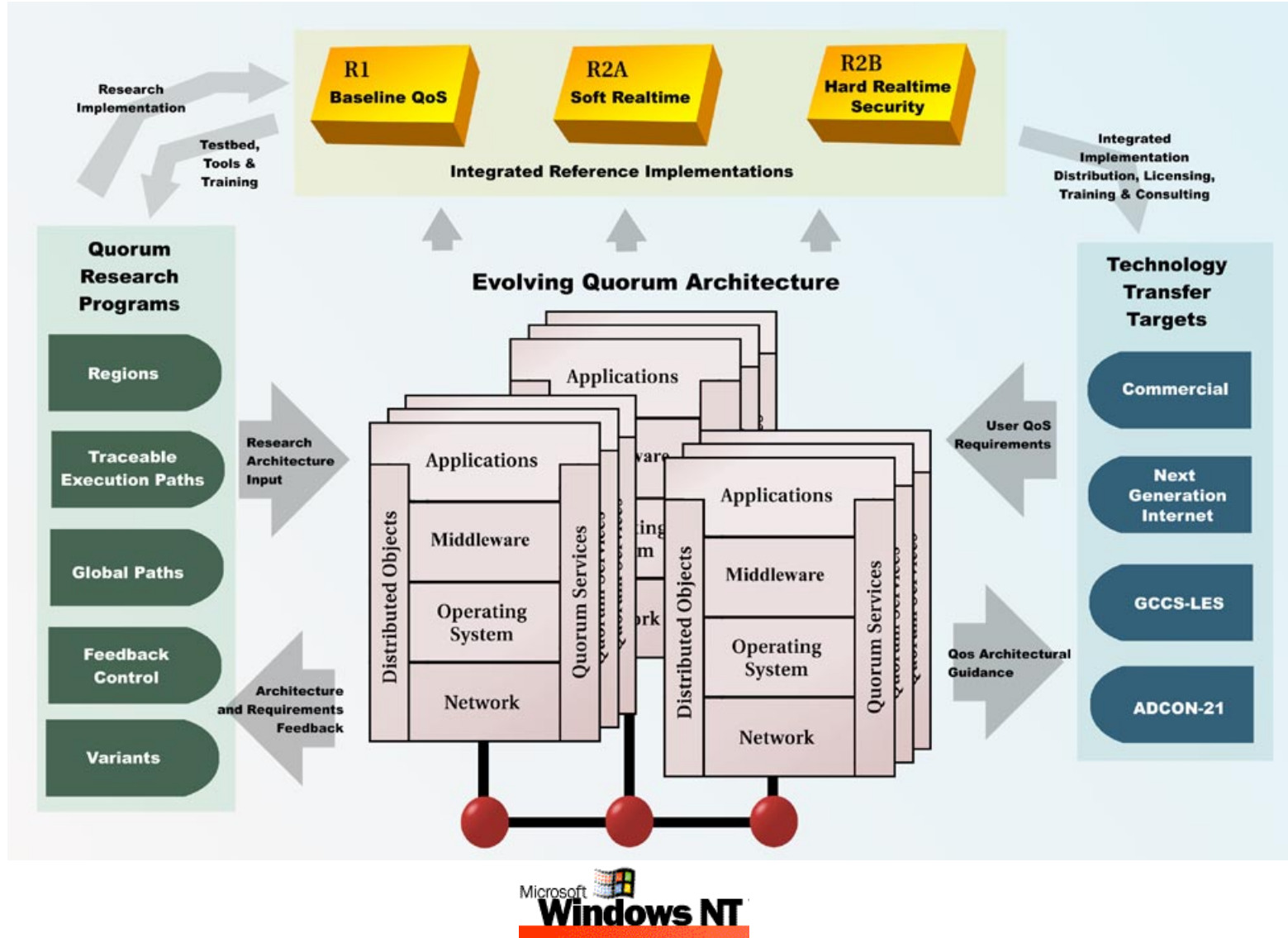


AdCon-21 Schedule Depends on Quorum



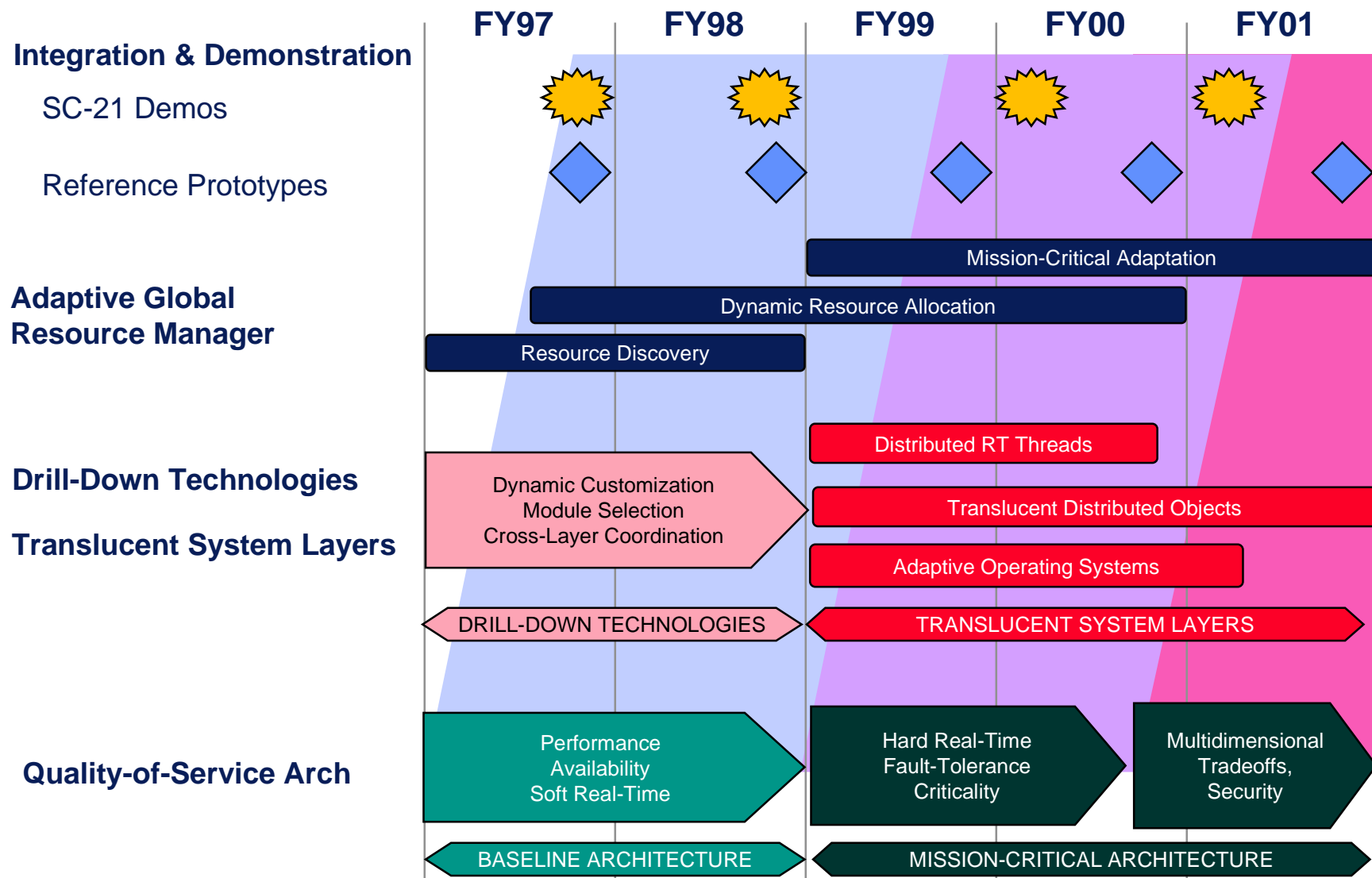


Quorum Integration Effort Mediates Transition





Quorum Road Map





Quorum Goal



**Deliver Assured Dynamic Response to Mission-Critical Applications
in the Presence of Mixed Workloads**

Command & Control

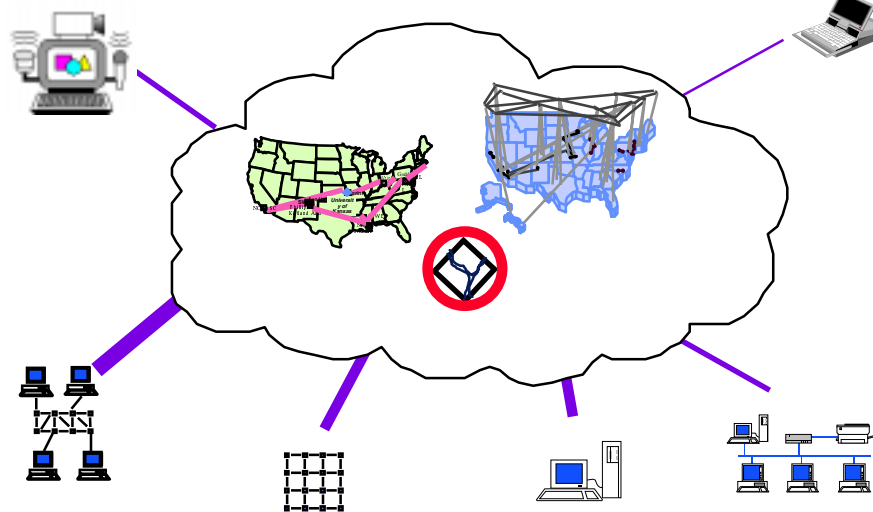


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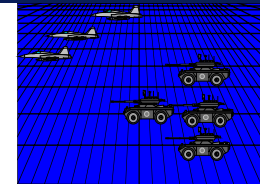
Combat Control



Hard Real-Time

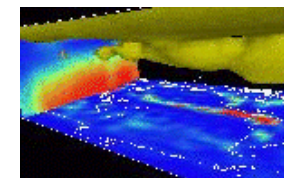


Modeling & Simulation



Mixed workload

Metacomputing



High Performance